MiRAC/AMALi-Team

AFLUX, 20.03.2019

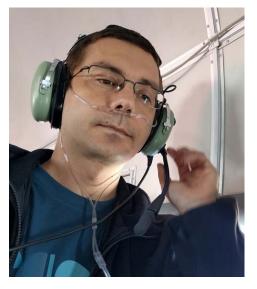


Susanne



Mario





Birte

Pavel

MiRAC

Microwave Radar/radiometer for Arctic Clouds

• Frequency Modulated Continuous Wave (FMCW) radar:

 \odot 25° inclined with respect to nadir

• Radar reflectivity \rightarrow Cloud profiles

 $\,\circ\,$ IWC, LWC, precipitation, snowfall rate

Doppler spectra

○ Radar contains passive channel at 89 GHz → Brightness Temperature
 ○ LWP, distinguish ice and ocean

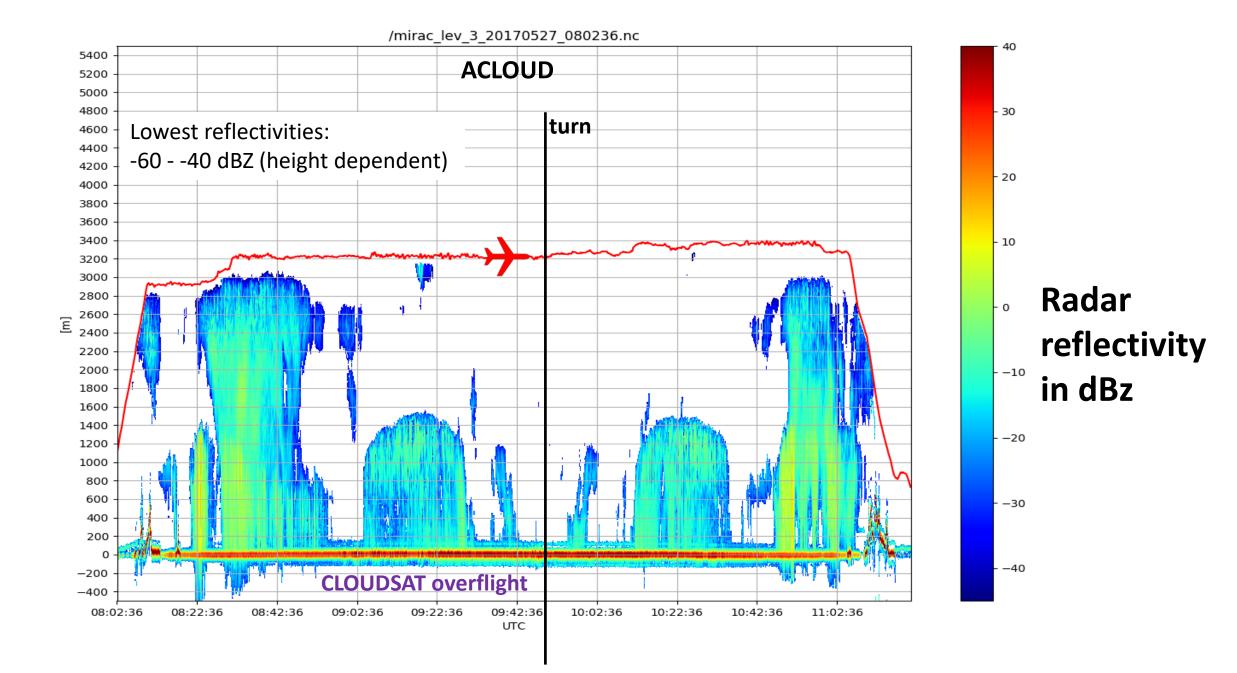
• Radiometer:

 \circ Nadir pointing

• Brightness Temperature at 243 GHz, 340 GHz and six channels at 183 GHz

Humidity profiles

- Ice particles properties
- Integrated Water Vapor (IWV)
- Liquid Water Path (LWP)



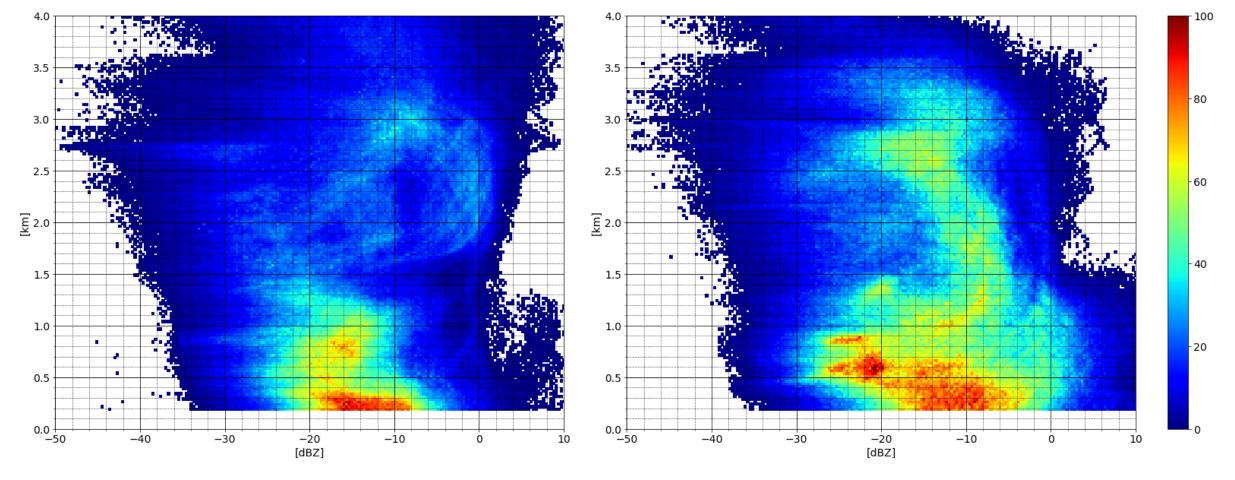
Preferred flight conditions

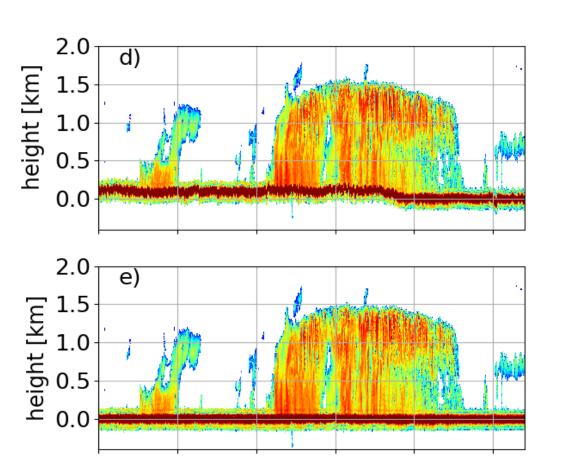
- 1. 490 ft (150 m) above cloud
- 2. > 8200 ft (2500 m) above sea level
- 3. straight legs preferred
- 4. Above ocean or sea ice

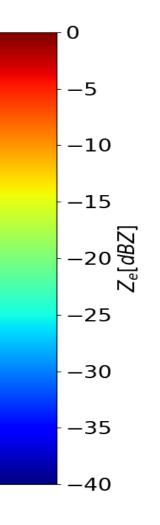
Contour Frequency by Altitude Diagramms
(CFADs)Measurements in total during ACLOUD:
 $40.5 h \rightarrow 52 \%$ of ACLOUD flights

AMSR-2 Uni Bremen: Sea ice

Ocean







Processing



Radar Calibration Flight

- **Conditions:** clear sky or thin clouds over calm ocean (Radar should receive surface signal)
- Calm weather conditions
- Variation of flight conditions (at 10000 ft):
 ▶ Pitch ε: 0-5°(as far as it is safe), three times
 ▶ Roll ρ: as much as possible, left-right-neutral → three times
 ▶ Altitude: flying up and down for three
 - times*,* 500 ft

>Needs to be discussed with pilots

