## Statistical Mechanics of Deep Learning - Problem set 9

## Winter Term 2024/25

The problem set will be discussed in the seminar on Monday 16.12.2024, 9:15.

## 18. Generalization of the maximally stable vector 4+4+4 Points

To compute the generalization error of the maximally stable vector e.g. from the adatron rule, consider the corresponding cost function

$$V(\Delta) = \frac{1}{2}(\Delta - \kappa)^2 \theta(\kappa - \Delta)$$

(a) Start by showing that  $\Delta_0(x,t)$  which minimizes  $V(\Delta) + \frac{(\Delta-t)^2}{2x}$ , is given by

$$\Delta_0(x,t) = \begin{cases} \frac{t + \kappa x}{1 + x} &, \ t < \kappa \\ t &, \ t \ge \kappa. \end{cases}$$

(b) Use the result obtained in part (a) in

$$1 - R^2 = 2\alpha \int \mathbf{D}t \left(\Delta_0(x, t) - t\right)^2 H\left(-\frac{Rt}{\sqrt{1 - R^2}}\right)$$

and

$$R = \frac{2\alpha}{\sqrt{2\pi(1-R^2)}} \int Dt \ \Delta_0(x,t) \exp\left(-\frac{R^2t^2}{2(1-R^2)}\right)$$

and consider the limit  $x \to \infty$  which corresponds to choosing the optimal  $\kappa$ . Show that the above equations reduces to

(1) 
$$1 - R^2 = 2\alpha \int_{-\infty}^{\kappa_{opt}} \mathbf{D}t \left(\kappa_{opt} - t\right)^2 H\left(-\frac{Rt}{\sqrt{1 - R^2}}\right)$$

and

(2) 
$$R = \frac{2\alpha}{\sqrt{2\pi(1-R^2)}} \int_{-\infty}^{\kappa_{opt}} \mathbf{D}t \left(\kappa_{opt} - t\right) \exp\left(-\frac{R^2 t^2}{2(1-R^2)}\right)$$

(c) Equations (1) and (2) can be used to determine  $\kappa_{opt}(\alpha)$  and  $R(\alpha)$  numerically. From the latter the generalization error can be computed using

$$\varepsilon = \frac{1}{\pi} \arccos(R).$$

Show that in the limit  $\alpha \to \infty$ , the asymptotic behavior of the generalization error is

$$\varepsilon(\alpha) \sim \frac{c}{\alpha \int_{-\infty}^{1} du (1-u) e^{-u^2/2c}} \sim \frac{0.5005}{\alpha}$$

with the constant c determined by the transcendental equation

$$\sqrt{\frac{c}{2\pi}} = \frac{\int_{-\infty}^{1} du (1-u)^{2} H(-u/\sqrt{c})}{\int_{-\infty}^{1} du (1-u) e^{-u^{2}/2c}}$$