Derivational order and ACGs

${\sf Gregory} \ {\sf M}. \ {\sf Kobele}^1 \qquad {\sf Jens} \ {\sf Michaelis}^2$

¹University of Chicago, Chicago, USA ²Bielefeld University, Bielefeld, Germany

ACG@10, Bordeaux, December 7-9, 2011

Greg & Jens (Chicago & Bielefeld)

Derivational order and ACGs

ACG@10 1 / 51

What good are ACGs?

• ACGs provide a way to understand MANY ideas from a uniform perspective

 Architectures for grammar 	(SP)
• Syntactico-centrism vs Parallelism	(SP, PdG, & CP)
 Grammar formalisms 	
CFHGs	(MK)
 CFG, LCFTG, MCFG 	(PdG, SP)
DTWT	(SS)
• MG	(SS)
:	
 Distributional learning 	(RY)
:	
 We want to add to the list: 	

• Timing

In other words, the nuclear scope of a quantifier is quite simply and quite literally its syntactic and semantic argument.

In other words, the nuclear scope of a quantifier is quite simply and quite literally its syntactic and semantic argument.

Thus on the cosubstitution approach, quantifier scope ambiguity is a matter of timing: quantifiers that enter later in the derivation take wider scope.

In other words, the nuclear scope of a quantifier is quite simply and quite literally its syntactic and semantic argument.

Thus on the cosubstitution approach, quantifier scope ambiguity is a matter of timing: quantifiers that enter later in the derivation take wider scope.

In other words, co-TAG has exactly the same weak and strong generative capacity as TAG.

Actually, an old approach to semantics (and other things)

Montague Grammar

(Montague)

[...] ambiguity can arise even when there is no element of intensionality, simply because quantifying terms may be introduced in more than one order.

Minimalist Grammars

(Gärtner & Michaelis; Kobele)

 $\left[\hdots \right]$ an expression may bind only those expressions that it c-commands when first merged

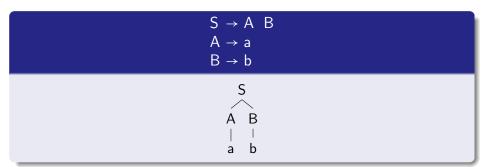
The problem:

Sometimes we have a semantic ambiguity without any obvious corresponding difference in the derivation tree.

The idea:

Enrich the derivation tree with information about order. (not only did I apply this rule, but I applied this rule *before that one*)

A concrete example



Example

The representation of a CFG derivation as a tree equates sequences of rewriting steps which rewrite nonterminal instances the same way. (Leftmost, rightmost, etc)

$$\langle S \Rightarrow AB \Rightarrow aB \Rightarrow ab \rangle \equiv \langle S \Rightarrow AB \Rightarrow Ab \Rightarrow ab \rangle$$

The goals:

- Make sense of the idea of 'timing' in terms of derivations
- Understand (in particular) co-substitution in TAGs in these terms
- If SGC/WGC unchanged, what is going on?

Our main claims are that:

- Third order ACGs provide an elegant description of the derivations of context-free formalisms.
- "Timing" is not derivational order

- Everyone's favourite example (Montague)
- **2** 3rd order ACGs and context-free derivations
- **3** Cosubstitution in TAGs

Montague Grammar

Quantifying In

Tree Adjoining Grammars

- co-substitution
- flexible composition

Minimalist Grammars

- Late adjunction
- 'hypothetical reasoning'

Montague Grammar (MG)

 MG has order sensitive rules in the form of Quantifying In (QI), namely, S14:

Rules of quantification

Montague Grammar (MG)

- MG has order sensitive rules in the form of Quantifying In (QI), namely, S14:
- QI has some complications we do not need to worry about right now: multiple occurrences of **he**_n can be affected by rule F_{10,n}
- QI is order sensitive in the sense that if we have a derivation $d = C[F_{10,i}(\alpha, D[F_{10,j}(\beta, \phi)])]$, then α takes semantic scope over β

An Example - De Re vs De Dicto Readings

• John seeks a unicorn.

De Re

There is a particular unicorn that John is looking for. $\exists y [\text{UNICORN}(y) \& \text{TRY}(\text{FIND}(y))(J)]$

De Dicto

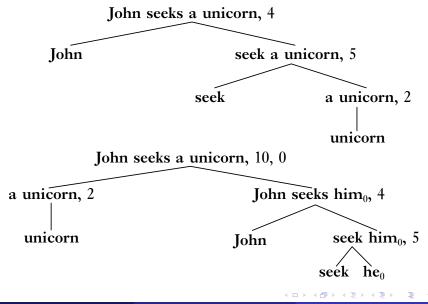
John will be satisfied with any unicorn. TRY $(\exists y [UNICORN(y) \& FIND(y)])(J)$

• Can be represented in terms of operator scope:

x seeks y

 $\operatorname{TRY}(\operatorname{FIND}(y))(x)$

Derivations for De Re vs De Dicto Readings



- A faithful ACG implementation of the derivation structure of MG might look as follows:
 - to each *n*-ary predicate (seek, love, ...) we associate a function symbol of type $np^n \rightarrow s$
 - to each common noun (**boy**, **unicorn**, ...) we associate a function symbol of type *n*
 - to each determiner (some, every, ...) we associate a function symbol of type $n \rightarrow d$
 - we have a function symbol **QI** of type ($np \rightarrow s$) \rightarrow ($d \rightarrow s$)
- This allows us to have abstract terms like the following:
 - $\mathbf{QI}(\lambda y^{np}.\mathbf{QI}(\lambda x^{np}.\mathbf{seek}(x)(y))(\mathbf{some}(\mathbf{unicorn})))(\mathbf{every}(\mathbf{boy}))$

- The lexica are as follows:
 - on the concrete phonology side, the symbol **QI** is interpreted as the (forwards application) combinator $\lambda xy.x(y)$ (and everything else is interpreted in the obvious way, given that all abstract types *n*, *d*, *np* and *s* are interpreted as the object type $o \rightarrow o$, the type of strings).
 - on the concrete semantic side, the symbol **QI** is interpreted as the (backwards application) combinator $\lambda xy.y(x)$.

- An alternative implementation substitutes for the type d the type $(np \rightarrow s) \rightarrow s$, and eliminates the symbol **QI**. Then we have abstract terms like:
 - $every(boy)(\lambda y^{np}.some(unicorn)(\lambda x^{np}.seek(x)(y)))$
- Under this alternative, the lexica are as follows:
 - The concrete phonological interpretation of a determiner every is as the function $\lambda x f. f(\text{every} \ x)$
 - The concrete semantic interpretation of a determiner **every** is as the function $\lambda x f. \forall (x)(f)$

- The ACG implementation does currently not deal with the ignored complexities of QI.
- The straightforward implementation takes the abstract terms to be pretty much isomorphic to the concrete semantic terms.
- The big picture (that it admittedly seems is not very clear in this presentation) is that:
 - higher order constants mark scope positions, and apply to lambda abstracts which make the variables in lower positions accessible.
 - In other words, 'timing' requires of an expression that it simultaneously be connected to both an underlying (argument) position, and a 'surface' (timing) position.

Strongly equivalent to monadic linear CFTGs

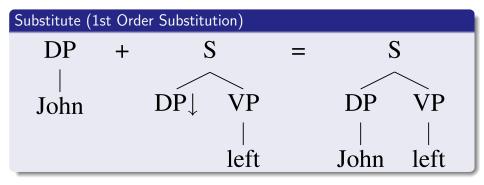
(Fujiyoshi & Kasai; Mönnich; Kepser & Rogers)

• Weakly equivalent to 2-MCFL_{wn}

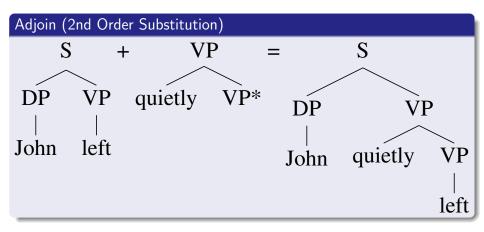
(Vijay-Shanker et al.; Seki et al.; Kanazawa)

A TAG consists of

initial trees a finite set of trees with leaves labelled by either terminals or X↓, where X is a nonterminal symbol auxiliary trees as before, but with exactly one leaf node labelled by X*, where X is the label of the root



∃ ▶ ∢



Barker's Innovation: Unrestricted Derivation and Scope

Fact

Linear CFTGs derive the same tree languages under all (IO, OI, unrestricted) derivation modes.

Barker:

 Γ scopes over Δ iff Γ was substituted in after a tree containing Δ was

Linear CFTGs Definition (repeated)

- G = $\langle N,T,P,s\rangle$ a linear CFTG
 - N the ranked alphabet of nonterminals
 - T the ranked alphabet of terminals
 - s the start symbol of rank 0 from N
 - P the production rules each of which of the form

$$a(x_1,\ldots,x_n) \to t$$

- $a \in N$ such that rank(a) = n
- x_1, \ldots, x_n variables of rank 0
- t a linear tree over $N \cup T \cup \{x_1, \dots, x_n\}$
- For expository reasons we assume that the start symbol $s \in N$ does not appear on the righthand side of any rule

Composition as second-order substitution

(de Groote and Pogodalla 2004)

 $G = \langle N, T, P, s \rangle$ a linear CFTG

Composition as second-order substitution

G = $\langle N,T,P,s\rangle$ a linear CFTG

 $\mathcal{G}_G = \langle \Sigma_G, \Sigma_T, \mathcal{L}_G, s \rangle$ associated 2nd order ACG

• $\Sigma_G = \langle N, \{\overline{p} \mid p \in P\}, \tau \rangle$ higher-order linear signature $\tau(\overline{p}) = a_1 \rightarrow \cdots \rightarrow a_m \rightarrow a$ $p \in P$ with skeleton $\langle a, a_1 \cdots a_m \rangle$

Linear CFTGs as ACGs Composition as second-order substitution (de Groote and Pogodalla 2004) $G = \langle N, T, P, s \rangle$ a linear CFTG $\mathcal{G}_G = \langle \Sigma_G, \Sigma_T, \mathcal{L}_G, s \rangle$ associated 2nd order ACG • $\Sigma_G = \langle N, \{ \overline{p} \mid p \in P \}, \tau \rangle$ higher-order linear signature $\tau(\overline{p}) = a_1 \to \cdots \to a_m \to a$ $p \in P$ with skeleton $\langle a, a_1 \cdots a_m \rangle$ • For $p = a(x_1, \ldots, x_n) \rightarrow t \in P$ with skeleton $\langle a, a_1 \cdots a_m \rangle$

• For $p = a(x_1, ..., x_n) \rightarrow t \in P$ with skeleton $(a, a_1 \cdots a_m)$ by induction, linear λ -term $[\![p]\!] \coloneqq \lambda y_1 \dots y_m \cdot \lambda x_1 \dots x_n \cdot |t|$

Composition as second-order substitution

G = $\langle N,T,P,s\rangle$ a linear CFTG

 $\mathcal{G}_G = \langle \Sigma_G, \Sigma_T, \mathcal{L}_G, s \rangle$ associated 2nd order ACG

• $\Sigma_G = \langle N, \{\overline{p} \mid p \in P\}, \tau \rangle$ higher-order linear signature $\tau(\overline{p}) = a_1 \rightarrow \cdots \rightarrow a_m \rightarrow a$ $p \in P$ with skeleton $\langle a, a_1 \cdots a_m \rangle$

• For $p = a(x_1, ..., x_n) \rightarrow t \in P$ with skeleton $\langle a, a_1 \cdots a_m \rangle$ by induction, linear λ -term $[\![p]\!] \coloneqq \lambda y_1 \dots y_m \cdot \lambda x_1 \dots x_n \cdot |t|$

 $\begin{aligned} |x_i| &= x_i \\ |f()| &= \lambda x \cdot (fx) \qquad f \in T \\ |f(t_1, \dots, t_k)| &= |t_1| + \dots + |t_k| \\ |a_j()| &= y_j \qquad a_j \text{ from skeleton} \\ |a_j(t_1, \dots, t_k)| &= y_j |t_1| \cdots |t_k| \end{aligned}$

Greg & Jens (Chicago & Bielefeld)

ACG@10 22 / 51

Linear CFTGs as ACGs Composition as second-order substitution (de Groote and Pogodalla 2004) $G = \langle N, T, P, s \rangle$ a linear CFTG $\mathcal{G}_G = \langle \Sigma_G, \Sigma_T, \mathcal{L}_G, s \rangle$ associated 2nd order ACG

- $\Sigma_G = \langle N, \{\overline{p} \mid p \in P\}, \tau \rangle$ higher-order linear signature $\tau(\overline{p}) = a_1 \rightarrow \cdots \rightarrow a_m \rightarrow a$ $p \in P$ with skeleton $\langle a, a_1 \cdots a_m \rangle$
- For $p = a(x_1, ..., x_n) \rightarrow t \in P$ with skeleton $\langle a, a_1 \cdots a_m \rangle$ by induction, linear λ -term $[\![p]\!] := \lambda y_1 \dots y_m \cdot \lambda x_1 \dots x_n \cdot |t|$
- $\mathcal{L}_G : \Sigma_G \to \Sigma_T$ $\mathcal{L}_G(a) = string^{rank(a)} \to string$ for $a \in N$ $\mathcal{L}_G(\overline{p}) = \llbracket p \rrbracket$ for $p \in P$

イロト イポト イヨト イヨト 二日

Composition as second-order substitution

G = $\langle N,T,P,s\rangle$ a linear CFTG

 $\mathcal{G}_G = \langle \Sigma_G, \Sigma_T, \mathcal{L}_G, s \rangle$ associated 2nd order ACG

- $\Sigma_G = \langle N, \{ \overline{p} \mid p \in P \}, \tau \rangle$ higher-order linear signature $\tau(\overline{p}) = a_1 \rightarrow \cdots \rightarrow a_m \rightarrow a$ $p \in P$ with skeleton $\langle a, a_1 \cdots a_m \rangle$
- For $p = a(x_1, \dots, x_n) \rightarrow t \in P$ with skeleton $\langle a, a_1 \cdots a_m \rangle$ by induction, linear λ -term $[\![p]\!] := \lambda y_1 \dots y_m \cdot \lambda x_1 \dots x_n \cdot |t|$
- $\mathcal{L}_G : \Sigma_G \to \Sigma_T$ $\mathcal{L}_G(a) = string^{rank(a)} \to string$ for $a \in N$ $\mathcal{L}_G(\overline{p}) = \llbracket p \rrbracket$ for $p \in P$

• $\Sigma_T = \langle \{ o \}, T, \widetilde{\tau} \rangle$ higher-order linear signature

$$\widetilde{\tau}(f) = string = o \rightarrow o \qquad f \in T$$

- (1日) - (1日)

< < >>

Linear CFTGs as ACGs Composition as second-order substitution (de Groote and Pogodalla 2004)

 $\mathcal{G}_G = \langle \Sigma_G, \Sigma_T, \mathcal{L}_G, s \rangle$ associated 2nd order ACG

 $G = \langle N, T, P, s \rangle$ a linear CFTG

• $\Sigma_G = \langle N, \{\overline{p} \mid p \in P\}, \tau \rangle$ higher-order linear signature $\tau(\overline{p}) = a_1 \rightarrow \cdots \rightarrow a_m \rightarrow a$

Composition as third-order substitution

G = $\langle N,T,P,s\rangle$ a linear CFTG

 $\mathcal{G}_G = \langle \Sigma_G, \Sigma_T, \mathcal{L}_G, s \rangle$ associated 2nd order ACG

• $\Sigma_G = \langle N, \{\overline{p} \mid p \in P\}, \tau \rangle$ higher-order linear signature $\tau(\overline{p}) = a_1 \rightarrow \cdots \rightarrow a_m \rightarrow a$

 $\mathcal{G}'_G = \langle \Sigma'_G, \Sigma_T, \mathcal{L}'_G, s \rangle$ 3rd order ACG resulting from \mathcal{G}_G

Composition as third-order substitution

G = $\langle N,T,P,s\rangle$ a linear CFTG

 $\mathcal{G}_G = \langle \Sigma_G, \Sigma_T, \mathcal{L}_G, s \rangle$ associated 2nd order ACG

• $\Sigma_G = \langle N, \{\overline{p} \mid p \in P\}, \tau \rangle$ higher-order linear signature $\tau(\overline{p}) = a_1 \rightarrow \cdots \rightarrow a_m \rightarrow a$

 $\mathcal{G}_G' = \langle \Sigma_G', \Sigma_T, \mathcal{L}_G', s \rangle \text{ 3rd order ACG resulting from } \mathcal{G}_G$

• $\Sigma'_G = \langle N, \{\overline{p} \mid p \in P\}, \tau' \rangle$ higher-order linear signature $\tau'(\overline{p}) = trans(\tau(\overline{p})) = trans(a_1 \to \cdots \to a_m \to a)$

 $\begin{aligned} trans(s) &= s & s & \text{the start symbol} \\ trans(a) &= (a \to s) \to s & a \in N - \{s\} \\ trans(\alpha \to \beta) &= \alpha \to trans(\beta) \end{aligned}$

ヘロト 人間と 人間と 人間と

Example grammar

<u>CFTG</u>

$p_1 = S \rightarrow f(T(c), G(c))$

- $p_2 = T(x) \rightarrow f(T(x), G(c))$
- $p_3 = G(x) \rightarrow h(x)$
- $p_4 = T(x) \rightarrow G(x)$

2nd order ACG

- $\overline{p}_1 \quad : \quad T \to G \to S$
- \overline{p}_2 : $T \to G \to T$
- \overline{p}_3 : G
- \overline{p}_4 : $G \rightarrow T$

(日) (周) (三) (三)

Example grammar

<u>CFTG</u>

p_1	=	S	\rightarrow	f(T(c), G(c))
p_2	=	T(x)	\rightarrow	$f(\mathbf{T}(x), \mathbf{G}(c))$
p_3	=	G(x)	\rightarrow	h(x)
p_4	=	T(x)	\rightarrow	G(x)

2nd order ACG

 $\overline{p}_1 \quad : \quad T \to G \to S$

 \overline{p}_2 : $T \to G \to T$

 \overline{p}_3 : G

 \overline{p}_4 : $G \to T$

$\frac{3 \text{rd order ACG}}{\overline{p}_1} : T \to G \to S$

 $\overline{p}_2 \quad : \quad T \to G \to (T \to S) \to S$

$$\overline{p}_3 \quad : \quad \left(\begin{array}{c} \pmb{G} \rightarrow S \end{array} \right) \rightarrow S$$

 $\overline{p}_4 : \boldsymbol{G} \to (\boldsymbol{T} \to \boldsymbol{S}) \to \boldsymbol{S}$

◆□▶ ◆□▶ ◆ □▶ ◆ □▶ ● □ ● ● ● ●

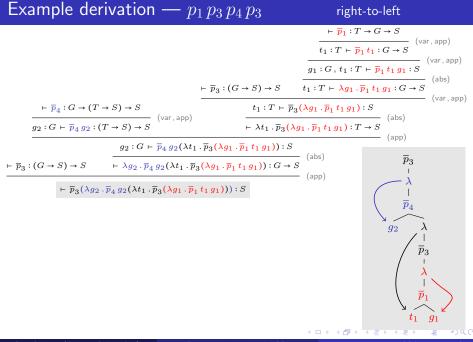
Example derivation — $p_1 p_4 p_3 p_3$ left-to-right $\vdash \overline{p}_1 : T \to G \to S$ $\frac{1}{t_1: T \vdash \overline{p}_1 t_1: G \to S}$ (var, app) $\frac{\vdash \overline{p}_4: G \to (T \to S) \to S}{g_2: G \vdash \overline{p}_4 g_2: (T \to S) \to S} \quad (\text{var, app}) \qquad \frac{\overline{g_1: G, t_1: T \vdash \overline{p}_1 t_1 g_1: S}}{g_1: G \vdash \lambda t_1 . \overline{p}_1 t_1 g_1: T \to S}$ (var, app) (abs) (app) $g_1: G, g_2: G \vdash \overline{p}_4 g_2(\lambda t_1, \overline{p}_1 t_1 g_1): S$ (abs) $\vdash \overline{p}_3: (G \to S) \to S \qquad g_2: G \vdash \lambda g_1 \cdot \overline{p}_4 g_2(\lambda t_1 \cdot \overline{p}_1 t_1 g_1): G \to S$ (app) $g_2: G \vdash \overline{p}_3(\lambda g_1, \overline{p}_4, g_2(\lambda t_1, \overline{p}_1, t_1, g_1)): S$ (abs) $\vdash \overline{p}_3: (G \to S) \to S \quad \vdash \lambda g_2 \cdot \overline{p}_3(\lambda g_1 \cdot \overline{p}_4 g_2(\lambda t_1 \cdot \overline{p}_1 t_1 g_1)): G \to S$ (app) $\vdash \overline{p}_{3}(\lambda g_{2} \cdot \overline{p}_{3}(\lambda g_{1} \cdot \overline{p}_{4} g_{2}(\lambda t_{1} \cdot \overline{p}_{1} t_{1} g_{1}))): S$

Example derivation — $p_1 p_4 p_3 p_3$ left-to-right $\vdash \overline{p}_1 : T \to G \to S$ (var, app) $t_1: T \vdash \overline{p}_1 t_1: G \to S$ (var, app) $\frac{\vdash \overline{p}_4: G \to (T \to S) \to S}{g_2: G \vdash \overline{p}_4 \, g_2: (T \to S) \to S}$ $g_1: G, t_1: T \vdash \overline{p}_1 t_1 g_1: S$ (var, app) (abs) $g_1: G \vdash \lambda t_1 \cdot \overline{p}_1 t_1 g_1: T \to S$ (app) $g_1: G, g_2: G \vdash \overline{p}_4 g_2(\lambda t_1, \overline{p}_1 t_1 g_1): S$ (abs) $\vdash \overline{p}_3: (G \to S) \to S \qquad g_2: G \vdash \lambda g_1 \cdot \overline{p}_4 g_2(\lambda t_1 \cdot \overline{p}_1 t_1 g_1): G \to S$ (app) $g_2: G \vdash \overline{p}_3(\lambda g_1, \overline{p}_4, g_2(\lambda t_1, \overline{p}_1, t_1, g_1)): S$ (abs) \overline{p}_3 $\vdash \overline{p}_3: (G \to S) \to S \quad \vdash \lambda g_2 \cdot \overline{p}_3(\lambda g_1 \cdot \overline{p}_4 g_2(\lambda t_1 \cdot \overline{p}_1 t_1 g_1)): G \to S$ (app) $\vdash \overline{p}_{3}(\lambda g_{2} \cdot \overline{p}_{3}(\lambda g_{1} \cdot \overline{p}_{4} g_{2}(\lambda t_{1} \cdot \overline{p}_{1} t_{1} g_{1}))): S$ \overline{p}_4 q_2 \boldsymbol{q}

Image: Image:

Example derivation — $p_1 p_3 p_4 p_3$ right-to-left $\vdash \overline{p}_1 : T \to G \to S$ $\frac{1}{t_1: T \vdash \overline{p}_1 t_1: G \rightarrow S} \quad (\text{var, app})$ $\frac{1}{g_1:G, t_1:T \vdash \overline{p}_1 t_1 g_1:S}$ (var, app) $\vdash \overline{p}_{3}: (G \to S) \to S \qquad \overline{t_{1}: T \vdash \lambda g_{1} \cdot \overline{p}_{1} t_{1} g_{1}: G \to S}$ — (abs) (var, app) $\frac{ \vdash \overline{p}_4: G \to (T \to S) \to S}{g_2: G \vdash \overline{p}_4 \, g_2: (T \to S) \to S} \ (\text{var,app})$ $t_1: T \vdash \overline{p}_3(\lambda g_1 . \overline{p}_1 t_1 g_1) : S$ — (abs) $\vdash \lambda t_1 \cdot \overline{p}_3(\lambda g_1 \cdot \overline{p}_1 t_1 g_1) : T \to S$ (app) $g_2: G \vdash \overline{p}_4 g_2(\lambda t_1, \overline{p}_3(\lambda g_1, \overline{p}_1 t_1 g_1)): S$ (abs) $\vdash \overline{p}_3 : (G \to S) \to S \qquad \vdash \lambda g_2 \cdot \overline{p}_4 \, g_2 \big(\lambda t_1 \cdot \overline{p}_3 \big(\lambda g_1 \cdot \overline{p}_1 \, t_1 \, g_1\big)\big) : G \to S$ (app) $\vdash \overline{p}_3(\lambda g_2 . \overline{p}_4 g_2(\lambda t_1 . \overline{p}_3(\lambda g_1 . \overline{p}_1 t_1 g_1))) : S$

・ロト ・ 同ト ・ ヨト ・ ヨト -



Back towards the object language

The transformation g which identifies 'equivalent' derivations:

$$\overline{p} \longmapsto \begin{cases} \overline{p} & \text{if } p \in P \text{ is a non-lifted rule} \\ \\ \lambda y_1 \dots y_m f \cdot f(\overline{p} y_1 \cdots y_m) & \text{otherwise} \end{cases}$$

• This actually maps a derivation with order information (qua third order lambda term) to a derivation tree, i.e.

a representation which keeps track only of which rule was used to rewrite which nonterminal, and not the relative order in which the rules were used.

Example

The transformation g which identifies 'equivalent' derivations:

$$\overline{p} \longmapsto \begin{cases} \overline{p} & \text{if } p \in P \text{ is a non-lifted rule} \\ \\ \lambda y_1 \dots y_m f \cdot f(\overline{p} y_1 \cdots y_m) & \text{otherwise} \end{cases}$$

•
$$\overline{p}_3(\lambda g_2.\overline{p}_3(\lambda g_1.\overline{p}_4g_2(\lambda t_1.\overline{p}_1t_1g_1)))$$
 left-to-right
and

 $\overline{p}_3\left(\,\lambda g_2\,.\,\overline{p}_4\,g_2\left(\,\lambda t_1\,.\,\overline{p}_3\left(\,\lambda g_1\,.\,\overline{p}_1\,t_1\,g_1\,\right)\,\right)\,\right)$

both are identified as

 $\overline{p}_1(\overline{p}_4\overline{p}_3)\overline{p}_3$

transformation under g

3 1 4

right-to-left

The object language of the new ACG is gotten by 'composing' the map g which turns a new abstract term into the old 'IO' one, and the original lexicon. (Note that this simply reuses the original ACG's lexicon — the object language of the new ACG is obtained by first translating it back into the old ACG, and then interpreting the old ACG as usual.)

We need to prove that the translation *trans* over types engenders an ACG whose abstract language exactly corresponds to the derivations of the original linear context-free tree grammar.

• One problem: the notion of derivation is not rich enough. We need to enrich it with information about which nonterminal is being rewritten. One way to do this is to redefine the notion of derivation:

$$\Rightarrow \subseteq (T_{\Sigma} \times P \times \mathbb{N}) \times T_{\Sigma}$$

That is, the one step derivation relation is between a tree (a sentential form), a rule, a natural number, and another tree:

 $C[A(t_1,\ldots,t_k)] \Rightarrow_{\mathbf{n}}^{p} C[t[t_1,\ldots,t_k]]$

if there are exactly n-1 nonterminal symbols to the left of the bullet in $C[\bullet]$, and if there is some rule $p = A(x_1, \ldots, x_k) \rightarrow t$. Now we want to say that each type derivation of an abstract term (a term in the abstract language) can be put into correspondence with a unique derivation in the CFTG, and what properties this correspondence should have.

- We will be interested in canonical (β-reduced, but η-long) terms. That is, in terms where all argument positions are explicitly filled, but where all applications have been computed.
- Note that the abstract language is a subset of the following:

$$L := \delta Y_1 \cdots Y_m \mid \rho Y_1 \cdots Y_m \lambda Y.L$$

where δ is a rule rewriting the start symbol, and ρ is not.

The object language

- To define a mapping 《·》 from such terms to derivations in the underlying CFTG, we first need to be able to turn a term into a sentential form. We do this in the following way:
- For each nonterminal T in the CFTG, there is a type T in the ACG. We introduce a new zero-place constant T of type T for each nonterminal T. We define the lexicon L" to be the extension of L' which maps each T to

$$\mathcal{L}''(\overline{T}) = \lambda x_1 \dots x_{rank(T)} \dots T x_1 \dots x_{rank(T)}$$

For $M \in \Lambda(\Sigma'_G)$ of atomic type with $FV(M) = \{y_1, \ldots, y_m\}$ we define

$$\llbracket M \rrbracket \coloneqq \mathcal{L}''((\lambda y_1, \dots, y_m \cdot M) \overline{T}_1 \cdots \overline{T}_m),$$

where $y_i: T_i$. Now $\llbracket M \rrbracket$ is simply the sentential form which M represents.

Greg & Jens (Chicago & Bielefeld)

ACG@10 33 / 51

The object language

- We can define the translation from terms to derivations after introducing the following notation: Let |λx. M| denote the number of free variables which occur to the left of the first occurrence of x in M.
- Note, this definition treats the λ -term as a syntactic object it distinguishes between terms which are β , η -equivalent. This is why we are working with the unique representative of a β , η -equivalence class which is β -reduced and η -long.
- Formally, define for any set B, any a being a constant or variable, and any lambda terms M and N:

$$str(B, a) = \begin{cases} \varepsilon & \text{if } a \in B \\ a & \text{otherwise} \end{cases}$$

$$str(B, \lambda x . M) = str(B \cup \{x\}, M)$$

$$str(B, (MN)) = str(B, M)^{\circ} str(B, N)$$

Then set $|\lambda x \cdot M| \coloneqq |u|$, where $str(C, M[x \to \bullet]) = u \bullet w$

• The translation can be given as

$$\langle\!\langle M \rangle\!\rangle = \left\{ \begin{array}{ll} S \ \Rightarrow_1^\delta & \llbracket M \rrbracket & \text{if } M = \delta \ y_1 \cdots y_m \\ \\ \langle\!\langle M \rangle\!\rangle \ \Rightarrow_{n+1}^\rho & \llbracket M \rrbracket & \text{if } M = \rho \ y_1 \cdots \ y_m \ \lambda y.N \\ \\ & \text{and if} & n = |\lambda y.N| \end{array} \right.$$

Claim

For every term M of the abstract language $\mathcal{A}(\mathcal{G}'_G)$, $\langle\!\langle M \rangle\!\rangle$ is a derivation in G of $[\![M]\!]$.

Translating back to ACGs

•
$$\langle\!\langle S \Rightarrow_1^{\delta} D' \rangle\!\rangle^{-1} = \llbracket D' \rrbracket (\lambda \vec{y} . \delta \vec{y})$$

•
$$\llbracket \phi \Rightarrow_{n+1}^{\rho} D' \rrbracket (M) = \llbracket D' \rrbracket (\lambda \vec{x} \vec{u} \vec{v} . \rho \vec{x} \lambda z . (M \vec{u} z \vec{v}))$$

such that $n = |\lambda z \cdot (M \vec{u} z \vec{v})|$

$$\bullet \ \llbracket \phi \rrbracket (M) = M$$

Claim

For every complete derivation D of t, $[[\langle D \rangle]^{-1}] = t$. Moreover, $\langle \cdot \rangle^{-1}$ is the inverse of $\langle \cdot \rangle$.

- dequotienting of 'equivalent' derivations implicit in the use of derivation trees
- but easy to use because substitution is managed by β -reduction
- canonical terms correspond exactly to derivations

• Some person left.

 $S \rightarrow s(DP, v)$ $DP \rightarrow d(det, NP)$ $NP \rightarrow n$

• Some person from Jamaica left.

$$DP \to d(det, NP'(NP))$$
$$NP'(x) \to NP'(np(x, pp(p, DP)))$$
$$NP'(x) \to x$$
$$DP \to name$$

$$\begin{split} S &\Rightarrow s(DP, v) \\ &\Rightarrow s(d(det, NP'(NP)), v) \\ &\Rightarrow s(d(det, NP'(n)), v) \\ &\Rightarrow s(d(det, NP'(np(n, pp(p, DP)))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, DP))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, NP'(NP))))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, NP)))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, n)))), v) \end{split}$$

$$\begin{split} S &\Rightarrow s(DP, v) \\ &\Rightarrow s(d(det, NP'(NP)), v) \\ &\Rightarrow s(d(det, NP'(n)), v) \\ &\Rightarrow s(d(det, NP'(np(n, pp(p, DP)))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, DP))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, NP'(NP))))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, NP)))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, NP)))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, n)))), v) \end{split}$$

3 🕨 🖌 3

$$\begin{split} S &\Rightarrow s(DP, v) \\ &\Rightarrow s(d(det, NP'(NP)), v) \\ &\Rightarrow s(d(det, NP'(n)), v) \\ &\Rightarrow s(d(det, NP'(np(n, pp(p, DP)))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, DP))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, NP'(NP))))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, NP)))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, NP)))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, n)))), v) \end{split}$$

$$\begin{split} S &\Rightarrow s(DP, v) \\ &\Rightarrow s(d(det, NP'(NP)), v) \\ &\Rightarrow s(d(det, NP'(n)), v) \\ &\Rightarrow s(d(det, NP'(np(n, pp(p, DP)))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, DP))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, NP'(NP))))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, NP)))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, NP)))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, n)))), v) \end{split}$$

$$\begin{split} S &\Rightarrow s(DP, v) \\ &\Rightarrow s(d(det, NP'(NP)), v) \\ &\Rightarrow s(d(det, NP'(n)), v) \\ &\Rightarrow s(d(det, NP'(np(n, pp(p, DP)))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, DP))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, NP'(NP))))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, NP)))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, n)))), v) \end{split}$$

$$S \Rightarrow s(DP, v)$$

$$\Rightarrow s(d(det, NP'(NP)), v)$$

$$\Rightarrow s(d(det, NP'(n)), v)$$

$$\Rightarrow s(d(det, NP'(np(n, pp(p, DP)))), v)$$

$$\Rightarrow s(d(det, np(n, pp(p, DP))), v)$$

$$\Rightarrow s(d(det, np(n, pp(p, d(det, NP'(NP))))), v)$$

$$\Rightarrow s(d(det, np(n, pp(p, d(det, NP)))), v)$$

3 🕨 🖌 3

$$\begin{split} S &\Rightarrow s(DP, v) \\ &\Rightarrow s(d(det, NP'(NP)), v) \\ &\Rightarrow s(d(det, NP'(n)), v) \\ &\Rightarrow s(d(det, NP'(np(n, pp(p, DP)))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, DP))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, NP'(NP))))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, NP)))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, NP)))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, n)))), v) \end{split}$$

3 🕨 🖌 3

$$\begin{split} S &\Rightarrow s(DP, v) \\ &\Rightarrow s(d(det, NP'(NP)), v) \\ &\Rightarrow s(d(det, NP'(n)), v) \\ &\Rightarrow s(d(det, NP'(np(n, pp(p, DP)))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, DP))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, NP'(NP))))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, NP)))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, NP)))), v) \\ &\Rightarrow s(d(det, np(n, pp(p, d(det, n)))), v) \end{split}$$

$$S \rightarrow s(DP, v) \qquad (\rho_S)$$

$$DP \rightarrow d(det, NP'(NP)) \qquad (\rho_{DP})$$

$$NP \rightarrow n \qquad (\rho_N)$$

$$NP'(x) \rightarrow NP'(np(x, pp(p, DP))) \qquad (\rho_{NP'_a})$$

$$NP'(x) \rightarrow x \qquad (\rho_{NP'_b})$$

$$S \rightarrow s(DP, v) \qquad DP \rightarrow S \qquad (\rho_S)$$
$$DP \rightarrow d(det, NP'(NP)) \qquad (\rho_{DP})$$
$$NP \rightarrow n \qquad (\rho_N)$$
$$NP'(x) \rightarrow NP'(np(x, pp(p, DP))) \qquad (\rho_{NP'_a})$$
$$NP'(x) \rightarrow x \qquad (\rho_{NP'_b})$$

$$S \to s(DP, v) \qquad DP \to S \qquad (\rho_S)$$
$$DP \to d(det, NP'(NP)) \qquad NP' \to NP \to DP \qquad (\rho_{DP})$$
$$NP \to n \qquad (\rho_N)$$
$$NP'(x) \to NP'(np(x, pp(p, DP))) \qquad (\rho_{NP'_a})$$
$$NP'(x) \to x \qquad (\rho_{NP'_b})$$

$S \rightarrow s(DP, v)$	$DP \rightarrow S$	(ho_S)
$DP \rightarrow d(det, NP'(NP))$	$NP' \rightarrow NP \rightarrow DP$	(ρ_{DP})
$NP \rightarrow n$	NP	(ho_N)
$NP'(x) \rightarrow NP'(np(x, pp(p, DP)))$		$(ho_{NP_a'})$
$NP'(x) \to x$		$(\rho_{NP'_b})$

$$S \to s(DP, v) \qquad DP \to S \qquad (\rho_S)$$
$$DP \to d(det, NP'(NP)) \qquad NP' \to NP \to DP \qquad (\rho_{DP})$$
$$NP \to n \qquad NP \qquad (\rho_N)$$
$$NP'(x) \to NP'(np(x, pp(p, DP))) \qquad NP' \to DP \to NP' \qquad (\rho_{NP'_a})$$
$$NP'(x) \to x \qquad (\rho_{NP'_b})$$

$S \to s(DP, v)$	$DP \rightarrow S$	(ho_S)
$DP \rightarrow d(det, NP'(NP))$	$NP' \rightarrow NP \rightarrow DP$	(ho_{DP})
$NP \rightarrow n$	NP	(ho_N)
$NP'(x) \rightarrow NP'(np(x, pp(p, DP)))$	$NP' \rightarrow DP \rightarrow NP'$	$(ho_{NP_a'})$
$NP'(x) \to x$	NP'	$(\rho_{NP_b'})$

$$\rho_{S}: DP \to S$$

$$\rho_{DP}: NP' \to NP \to DP$$

$$\rho_{N}: NP$$

$$\rho_{NP'_{a}}: NP' \to DP \to NP'$$

$$\rho_{NP'_{b}}: NP'$$

(日) (同) (三) (三)

$$\rho_{S}: DP \to S$$

$$\rho_{DP}: NP' \to NP \to DP$$

$$\rho_{N}: NP$$

$$\rho_{NP'_{a}}: NP' \to DP \to NP'$$

$$\rho_{NP'_{b}}: NP'$$

(日) (同) (三) (三)

$$\rho_{S}: DP \to S$$

$$\rho_{DP}: NP' \to NP \to DP$$

$$\rho_{N}: NP$$

$$\rho_{NP'_{a}}: NP' \to DP \to NP'$$

$$\rho_{NP'_{b}}: NP'$$

(日) (同) (三) (三)

$$\rho_{S} : DP \to S$$

$$\rho_{DP} : NP' \to NP \to (DP \to S) \to S$$

$$\rho_{N} : NP$$

$$\rho_{NP'_{a}} : NP' \to DP \to NP'$$

$$\rho_{NP'_{b}} : NP'$$

-

$$\rho_{S} : DP \to S$$

$$\rho_{DP} : NP' \to NP \to (DP \to S) \to S$$

$$\rho_{N} : NP$$

$$\rho_{NP'_{a}} : NP' \to DP \to NP'$$

$$\rho_{NP'_{b}} : NP'$$

< ロ > < 同 > < 三 > < 三

$$\rho_{S} : DP \to S$$

$$\rho_{DP} : NP' \to NP \to (DP \to S) \to S$$

$$\rho_{N} : (NP \to S) \to S$$

$$\rho_{NP'_{a}} : NP' \to DP \to NP'$$

$$\rho_{NP'_{b}} : NP'$$

э

$$\rho_{S} : DP \to S$$

$$\rho_{DP} : NP' \to NP \to (DP \to S) \to S$$

$$\rho_{N} : (NP \to S) \to S$$

$$\rho_{NP'_{a}} : NP' \to DP \to NP'$$

$$\rho_{NP'_{b}} : NP'$$

< ロ > < 同 > < 三 > < 三

And here the types lifted over S:

$$\rho_{S}: DP \to S$$

$$\rho_{DP}: NP' \to NP \to (DP \to S) \to S$$

$$\rho_{N}: (NP \to S) \to S$$

$$\rho_{NP'_{a}}: NP' \to DP \to (NP' \to S) \to S$$

$$\rho_{NP'_{b}}: NP'$$

э

And here the types lifted over S:

$$\rho_{S} : DP \to S$$

$$\rho_{DP} : NP' \to NP \to (DP \to S) \to S$$

$$\rho_{N} : (NP \to S) \to S$$

$$\rho_{NP'_{a}} : NP' \to DP \to (NP' \to S) \to S$$

$$\rho_{NP'_{b}} : NP'$$

э

And here the types lifted over S:

$$\begin{split} \rho_{S} &: DP \to S \\ \rho_{DP} &: NP' \to NP \to (DP \to S) \to S \\ \rho_{N} &: (NP \to S) \to S \\ \rho_{NP'_{a}} &: NP' \to DP \to (NP' \to S) \to S \\ \rho_{NP'_{b}} &: (NP' \to S) \to S \end{split}$$

э

Some person left

```
basic (2nd order):
```

```
\rho_{S}\left(\,\rho_{DP}\left(\,\rho_{NP'_{b}}\,\rho_{NP}\,\right)\,\right)
```

lifted (3rd order):

 $\rho_N(\lambda x_N . \rho_{NP'_b}(\lambda x_{NP} . \rho_{DP}(x_{NP} x_N \lambda x_D . \rho_S x_D))))$

• Some person from every city left basic:

 $\rho_{S}\left(\rho_{DP}\left(\rho_{NP_{a}^{\prime}}\left(\rho_{NP_{b}^{\prime}}\rho_{DP}\left(\rho_{NP_{b}^{\prime}}\rho_{NP}\right)\right)\rho_{NP}\right)\right)$

lifted

 ${}_{np} \cdot \rho_{NP'_{b}}(\lambda x_{np'} \cdot \rho_{DP}(x_{np'} x_{np} (\lambda x_{d} \cdot \rho_{NP'_{b}}(\lambda x_{np'} \cdot \rho_{NP'_{a}}(x_{np'} x_{d} (\lambda x_{np'} \cdot \rho_{N}(\lambda x_{np} \cdot \rho_{DP}(x_{np'} x_{np} (\lambda x_{d} \cdot \rho_{S} x_{d}))))$

derivation order does not permit surface scope in:

• every person from a city left.

derivation order does not permit surface scope in:

• every person from a city left.

The problem:

the most deeply embedded quantifier cannot be introduced until *after* its 'argument' position is present, which is introduced only once its containing DP is present

derivation order does not permit surface scope in:

every person from a city left.

The problem:

the most deeply embedded quantifier cannot be introduced until *after* its 'argument' position is present, which is introduced only once its containing DP is present

Example

Every derivation begins: $\langle\!\langle S \Rightarrow s(DP, v) \rangle\!\rangle^{-1} =$

$$\lambda x_D.\rho_S(x_D)$$

derivation order does not permit surface scope in:

every person from a city left.

The problem:

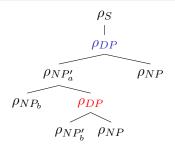
the most deeply embedded quantifier cannot be introduced until *after* its 'argument' position is present, which is introduced only once its containing DP is present

Example

Every derivation begins: $\langle\!\langle S \Rightarrow s(DP, v) \Rightarrow s(d(det, NP'(NP)), v)\rangle\!\rangle^{-1} = \lambda x_{NP'} x_N \cdot \rho_{DP} (x_{NP'} x_N \lambda x_D \cdot \rho_S(x_D))$

Constituency in derivations

A timing based approach to quantifier scope simply cannot derive surface scope relations between embedded scope-takers: the scope relations predicted are always inverted.



The possible derivations for t are given by h(t), where $h(\sigma(t_1, \ldots, t_n) \coloneqq \sigma \cdot \bigsqcup \{h(t_1), \ldots, h(t_n)\}$ $\rho_S \cdot (\rho_{DP} \cdot (\rho_{NP} \sqcup (\rho_{NP'_a} \cdot (\rho_{NP'_b} \sqcup (\rho_{NP'_b} \sqcup \rho_{NP}))))))$

- Barker wants scope relations such that $\rho_{DP} < \rho_{DP}$
- There is no derivation which provides this
- No system which derives this can be expressed in terms of derivations

Whatever people mean by "timing"

it is not describable in terms of rewriting order

- We simply lifted all of our types
 - because we wanted to look at every possible derivation order
- Barker only allows for cosubstitution of certain initial trees (the DPs)
 - this corresponds to us only lifting types ending in DP
 - the resulting signature has nothing to do with derivations

$$\rho_{S}: DP \to S$$

$$\rho_{DP}: NP' \to NP \to DP$$

$$\rho_{N}: NP$$

$$\rho_{NP'_{a}}: NP' \to DP \to NP'$$

$$\rho_{NP'_{b}}: NP'$$

 $\rho_{S}: DP \to S$ $\rho_{DP}: NP' \to NP \to DP$ $\rho_{N}: NP$ $\rho_{NP'_{a}}: NP' \to DP \to NP'$ $\rho_{NP'_{b}}: NP'$

- 4 回 ト - 4 回 ト

$$\rho_{S}: DP \to S$$

$$\rho_{DP}: NP' \to NP \to DP$$

$$\rho_{N}: NP$$

$$\rho_{NP'_{a}}: NP' \to DP \to NP'$$

$$\rho_{NP'_{b}}: NP'$$

$$\rho_{S} : DP \to S$$

$$\rho_{DP} : NP' \to NP \to (DP \to S) \to S$$

$$\rho_{N} : NP$$

$$\rho_{NP'_{a}} : NP' \to DP \to NP'$$

$$\rho_{NP'_{b}} : NP'$$

$$\rho_{S} : DP \to S$$

$$\rho_{DP} : NP' \to NP \to (DP \to S) \to S$$

$$\rho_{N} : NP$$

$$\rho_{NP'_{a}} : NP' \to DP \to NP'$$

$$\rho_{NP'_{b}} : NP'$$

$$\rho_{S} : DP \to S$$

$$\rho_{DP} : NP' \to NP \to (DP \to S) \to S$$

$$\rho_{N} : NP$$

$$\rho_{NP'_{a}} : NP' \to DP \to NP'$$

$$\rho_{NP'_{b}} : NP'$$

$$\begin{split} \rho_{S} &: DP \to S \\ \rho_{DP} &: NP' \to NP \to (DP \to S) \to S \\ \rho_{N} &: NP \\ \rho_{NP'_{a}} &: NP' \to DP \to NP' \\ \rho_{NP'_{b}} &: NP' \end{split}$$

-

$$\begin{split} \rho_{S} &: DP \to S \\ \rho_{DP} &: NP' \to NP \to (DP \to S) \to S \\ \rho_{N} &: NP \\ \rho_{NP'_{a}} &: NP' \to DP \to NP' \\ \rho_{NP'_{b}} &: NP' \end{split}$$

-

$$\rho_{S} : DP \to S$$

$$\rho_{DP} : NP' \to NP \to (DP \to S) \to S$$

$$\rho_{N} : NP$$

$$\rho_{NP'_{a}} : NP' \to DP \to NP'$$

$$\rho_{NP'_{b}} : NP'$$

$$\rho_{S} : DP \to S$$

$$\rho_{DP} : NP' \to NP \to (DP \to S) \to S$$

$$\rho_{N} : NP$$

$$\rho_{NP'_{a}} : NP' \to DP \to NP'$$

$$\rho_{NP'_{b}} : NP'$$

We still don't get the surface reading!

• but this time its easy to fix:

Barker's solution

allow a version of rule $\rho_{NP'_a}$ to directly select for a continuized DP:

$$\rho'_{NP'_a} \coloneqq NP' \to ((DP \to S) \to S) \to NP$$

A lexical solution

introduce new atomic type XP, and duplicate rules as appropriate:

$$XP \to d(det, NP'(NP)) \qquad (\rho_{XP})$$
$$NP'(x) \to NP'(np(x, pp(p, XP))) \qquad (\rho_{NP'_c})$$

lexically interpret $\mathcal{L}(XP) = \mathcal{L}((DP \to S) \to S)$

Cotags

- leave the realm of context-free grammar formalisms
- WGC and SGC preservation
 - NOT because IO and OI coincide on linear CFTGs
 - instead, because spellout involves going back through the $2^{\rm nd}$ order derivation term
- Complexity heuristics in ACG differ from those of TAG:
 - 'simpler' to deal with in-situ readings by making lexicon higher order than the abstract language ... (??)

Timing

- intuitive and oft-occuring
- not related to rewriting strategies
 - (we may have been the only ones to have thought this...)
- best seen as moving from *trees* to (3rd order) *terms*

Thank you!

1

・ロト ・ 日 ト ・ 田 ト ・