

26. (Rigidly rotating rod) The purpose of this exercise is to work out the stress tensor of a rotating rod in Minkowski spacetime. The rod is assumed to rotate in the  $(x, y)$  plane about the  $z$ -axis, with angular velocity  $\omega$ .

(a) We first introduce (space-fixed) cylindrical coordinates  $(t, r, z, \phi)$  about the  $z$ -axis. Show that the Minkowski line element  $ds^2 = -dt^2 + dx^2 + dy^2 + dz^2$  becomes

$$ds^2 = -dt^2 + dr^2 + r^2 d\phi^2 + dz^2. \quad (1)$$

(b) Next we introduce co-rotating cylindrical coordinates  $\hat{t} = t, \hat{r} = r, \hat{z} = z, \hat{\phi} = \phi + \omega t$ . Show that the line element becomes

$$ds^2 = -\left(1 - \omega^2 \hat{r}^2\right) d\hat{t}^2 - 2\hat{r}^2 \omega d\hat{\phi} d\hat{t} + d\hat{r}^2 + \hat{r}^2 d\hat{\phi}^2 + d\hat{z}^2 \quad (2)$$

(c) Finally, we introduce co-rotating (body fixed) ‘cartesian’ coordinates  $\hat{x} = \hat{r} \cos \hat{\phi}, \hat{y} = \hat{r} \sin \hat{\phi}$ . Show that

$$ds^2 = -\left(1 - \omega^2 \hat{r}^2\right) d\hat{t}^2 - 2\omega (\hat{x} d\hat{y} - \hat{y} d\hat{x}) d\hat{t} + d\hat{x}^2 + d\hat{y}^2 + d\hat{z}^2. \quad (3)$$

(d) In the rest frame of the rod (co-rotating coordinates), the rod is assumed to be of length  $\ell$ . Without loss of generality, we can assume that it points in the  $\hat{x}$  direction, and to simplify matters, we assume that it is reflection symmetric. We make the following ansatz for the stress tensor describing such a rod:

$$T^{\hat{t}\hat{t}} = \rho(|\hat{x}|)\Theta(\ell - |\hat{x}|)\delta(\hat{y})\delta(\hat{z}), \quad (4a)$$

$$T^{\hat{x}\hat{x}} = -\sigma(|\hat{x}|)\Theta(\ell - |\hat{x}|)\delta(\hat{y})\delta(\hat{z}), \quad (4b)$$

and all other components are zero. Transform this back to cylindrical non-rotating coordinates and show that

$$T^{\hat{t}\hat{t}} = \rho(\hat{r})\Theta(\ell - \hat{r})\frac{\delta(\hat{\phi} \bmod \pi)}{\hat{r}}\delta(\hat{z}), \quad (5a)$$

$$T^{\hat{r}\hat{r}} = -\sigma(\hat{r})\Theta(\ell - \hat{r})\frac{\delta(\hat{\phi} \bmod \pi)}{\hat{r}}\delta(\hat{z}), \quad (5b)$$

$$(5c)$$

where

$$\delta(\hat{\phi} \bmod \pi) = \sum_{k \in \mathbb{N}} \delta(\hat{\phi} + k\pi) = \delta(\sin \hat{\phi}), \quad (6)$$

and where all other components are again zero.

- (e) Transform the result now further back to the original, non-rotating (space-fixed) cylindrical coordinates  $(t, r, z, \phi)$ , and show that

$$T^{tt} = \rho(r)\Theta(\ell - r)\frac{\delta(\phi + \omega t \bmod \pi)}{r}\delta(z), \quad (7a)$$

$$T^{t\phi} = -\omega\rho(r)\Theta(\ell - r)\frac{\delta(\phi + \omega t \bmod \pi)}{r}\delta(z), \quad (7b)$$

$$T^{rr} = -\sigma(r)\Theta(\ell - r)\frac{\delta(\phi + \omega t \bmod \pi)}{r}\delta(z), \quad (7c)$$

$$T^{\phi\phi} = \omega^2\rho(r)\Theta(\ell - r)\frac{\delta(\phi + \omega t \bmod \pi)}{r}\delta(z). \quad (7d)$$

- (f) Based on the formula of the previous item (or otherwise), show that conservation  $\partial_\mu T^{\mu\nu} = 0$  (here  $\partial_\mu$  is the covariant derivative of Minkowski spacetime, which is equal to the ordinary partial derivative in non-rotating cartesian coordinates  $(t, x, y, z)$ , but which has a non-zero Christoffel symbol in the coordinates  $(t, r, z, \phi)$ . You may either compute these, or first further transform the stress tensor to the coordinates  $(t, x, y, z)$ .) is equivalent to the single condition

$$\sigma(r) = \omega^2 \int_r^\ell r' \rho(r') dr'. \quad (8)$$

- (g) What is the physical interpretation of  $\sigma$  and  $\rho$ ?
- (h) What is the form of the stress tensor the special case  $\rho(r) = \rho_0$  for  $r < \ell$  and  $\rho(r) = 0$  for  $r \geq \ell$ ?
- (i) Work out the quadrupole tensor for the stress tensor in the previous item. You must work in cartesian (space-fixed) coordinates.